RENESAS

DATASHEET

ISL90810

Single Digitally Controlled Potentiometer (XDCP™) Low Noise/Low Power/I²C Bus/256 Taps

FN8234 Rev 3.00 September 10, 2015

The ISL90810 integrates a digitally controlled potentiometer (XDCP) on a monolithic CMOS integrated circuit.

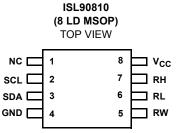
The digitally controlled potentiometers are implemented with a combination of resistor elements and CMOS switches. The position of the wipers are controlled by the user through the I^2C bus interface. Each potentiometer has an associated Wiper Register (WR) that can be directly written to and read by the user. The contents of the WR controls the position of the wiper. When powered on the ISL90810's wiper will always commence at mid-scale (128 tap position).

The DCP can be used as three-terminal potentiometer or as two-terminal variable resistor in a wide variety of applications including control, parameter adjustments, and signal processing.

Features

- 256 resistor taps 0.4% resolution
- I²C serial interface with write/read capability
- · Power-on preset to mid-scale (128 tap position)
- Wiper resistance: 70Ω typical @ 3.3V
- Standby current 5µA max
- Power supply: 2.7V to 5.5V
- 50kΩ, 10kΩ total resistance
- 8 Ld MSOP
- · Pb-free plus anneal available (RoHS compliant)

Pinout



Orderina	Information
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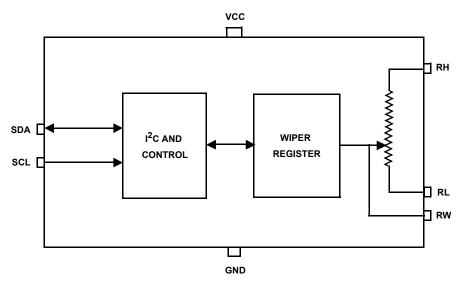
PART NUMBER	PART MARKING	R _{TOTAL} (kΩ)	TEMP RANGE (°C)	PACKAGE	PKG. DWG#
ISL90810WIU8Z* (Note) (No longer available, recommended replacement: ISL90810UAU8Z-TK)	DEN	10	-40 to +85	8 Ld MSOP (Pb-free)	M8.118
ISL90810WAU8Z* (Note) (No longer available, recommended replacement: ISL90810UAU8Z-TK)	810WA	10	-40 to +105	8 Ld MSOP (Pb-free)	M8.118
ISL90810UIU8Z* (Note)	DEM	50	-40 to +85	8 Ld MSOP (Pb-free)	M8.118
ISL90810UAU8Z* (Note)	810UA	50	-40 to +105	8 Ld MSOP (Pb-free)	M8.118

*Add "-TK" suffix for tape and reel.

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.



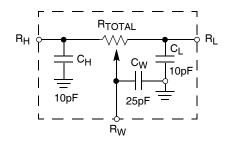
Block Diagram



Pin Descriptions

MSOP PIN	SYMBOL	DESCRIPTION
1	NC	No connection
2	SCL	I ² C interface clock
3	SDA	Serial data I/O for the I ² C interface
4	GND	Ground
5	RW	"Wiper" terminal of the DCP
6	RL	"Low" terminal of the DCP
7	RH	"High" terminal of the DCP
8	V _{CC}	Power supply

Equivalent Circuitry





Absolute Maximum Ratings

Storage Temperature65°C to +150°C Voltage at Any Digital Interface Pin
With Respect to V _{SS} 0.3V to V _{CC} +0.3V
V _{CC} 0.3V to +6V
Voltage at Any DCP Pin With
Respect to V _{SS} 0.3V to V _{CC}
Lead Temperature (Soldering, 10s)+300°C
I _W (10s)
Latchup Class II, Level A @ +105°C
ESD
HBM
MM

Thermal Information

Thermal Resistance (Typical, Note 1)	θ _{JA} (°C/W)
8 Ld MSOP Package	130
Maximum Junction Temperature (Plastic Package	+150°C

Recommended Operating Conditions

Industrial	40°C to +85°C
Automotive	40°C to +105°C
V _{CC}	2.7V to 5.5V
Power Rating	
Wiper Current	±3.0mA

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTES:

1. θ_{JA} is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief TB379 for details.

SYMBOL	PARAMETER	TEST CONDITIONS		MIN	TYP (Notes 2)	МАХ	UNIT
R _{TOTAL}	R _H to R _L Resistance	W, U versions respectively			10, 50		kΩ
	R _H to R _L Resistance Tolerance			-20		+20	%
R _W	Wiper resistance	V _{CC} = 3.3V @ +25°C Wiper current = V _{CC} /R _{TOTAL}			70	200	Ω
C _H /C _L /C _W	Potentiometer Capacitance (Note 14, Equivalent circuitry)				10/10/25		pF
I _{LkgDCP}	Leakage on DCP pins (Note 14)	Voltage at pin from GND to V_{CC}			0.1	1	μA
VOLTAGE DIVID	ER MODE (0V @ RL; V _{CC} @ RH; me	easured at RW, unloaded)					
INL (Note 7)	Integral Non-Linearity			-1		1	LSB (Note 3)
DNL (Note 6) Differentia	Differential Non-Linearity	Monotonic over all tap positions	W option	-0.75		+0.75	LSB (Note 3)
			U option	-0.5		+0.5	LSB (Note 3)
ZSerror (Note 4)	Zero-Scale Error	W option			1	7	LSB (Note 3)
		U option			0.5	2	
FSerror (Note 5)	Full-Scale Error	W option			-1	0	LSB (Note 3)
		U option			-0.5	0	
TC _V (Notes 8, 14)	Ratiometric Temperature Coefficient	DCP Register set to 80 hex			±4		ppm/°C
RESISTOR MOD	E (Measurements between RW and F	RL with RH not connected, or betwe	en RW and	RH wit	h RL not con	nected)	
RINL (Note 12)	Integral Non-Linearity	DCP register set between 20 hex an Monotonic over all tap positions	nd FF hex.	-1		1	MI (Note 9)
RDNL (Note 6)	Differential Non-Linearity	DCP register set between 20 hex	W option	-0.75		+0.75	MI (Note 9)
		and FF hex. Monotonic over all tap U opositions		-0.5		+0.5	MI (Note 9)
Roffset (Note 10)	Offset	W option		0	1	7	MI (Note 9)
		U option			0.5	2	MI (Note 9)
TC _R (Notes 13, 14)	Resistance Temperature Coefficient	DCP register set between 20 hex and FF hex			±35		ppm/°C

Analog Specifications Over recommended operating conditions unless otherwise stated.

Operating Specifications Over the recommended operating conditions unless otherwise specified.

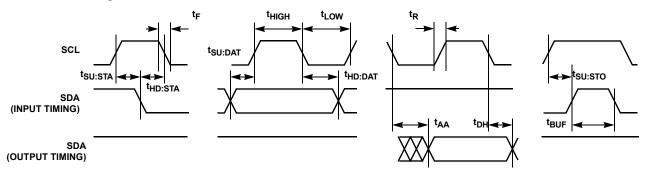
SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP (Note 1)	МАХ	UNITS
I _{CC1}	VC1VCC Supply Current (Volatile Write/Read) $f_{SCL} = 400 \text{kHz}$; SDA = Open; (for I2C, Active, Read and Volatile Write States only)			20	100	μA
I _{SB}	V _{CC} Current (Standby)	V _{CC} = +5.5V, I ² C Interface in Standby State, Temperature range from -40°C to +85°C		2	5	μA
		V_{CC} = +5.5V, I ² C Interface in Standby State, Temperature range from -40°C to +105°C		2	8	μA
		V_{CC} = +3.6V, I ² C Interface in Standby State, Temperature range from -40°C to +85°C		0.8	2	μA
		V_{CC} = +3.6V, I ² C Interface in Standby State, Temperature range from -40°C to +105°C		0.8	5	μA
I _{LkgDig}	Leakage Current at Pins SDA and SCL	Voltage at pin from GND to V_{CC}	-10		10	μA
t _{DCP} (Note 14)	DCP Wiper Response Time	SCL falling edge of last bit of DCP Data Byte to wiper change			1	μs
Vpor	Power-On Recall Voltage	Minimum V_{CC} at which memory recall occurs	1.8		2.6	V
V _{CC} Ramp	V _{CC} Ramp Rate		0.2			V/ms
t _D (Note 14)	Power-Up Delay	V_{CC} above Vpor, to DCP Initial Value Register recall completed, and $I^2 C$ Interface in standby state			3	ms
SERIAL INTERF	ACE SPECIFICATIONS				L L	
V _{IL}	SDA, and SCL Input Buffer LOW Voltage		-0.3		0.3*V _{CC}	V
V _{IH}	SDA, and SCL Input Buffer HIGH Voltage		0.7*V _{CC}		V _{CC} +0.3	V
Hysteresis (Note 14)	SDA and SCL Input Buffer Hysteresis		0.05* V _{CC}			V
V _{OL} (Note 14)	SDA Output Buffer LOW Voltage, Sinking 4mA		0		0.4	V
Cpin (Note 14)	SDA, and SCL Pin Capacitance				10	pF
f _{SCL}	SCL Frequency				400	kHz
t _{IN} (Note 14)	Pulse Width Suppression Time at SDA and SCL Inputs	Any pulse narrower than the max spec is suppressed.			50	ns
t _{AA} (Note 14)	SCL Falling Edge to SDA Output Data Valid	SCL falling edge crossing 30% of V $_{\rm CC}$, until SDA exits the 30% to 70% of V $_{\rm CC}$ window.			900	ns
t _{BUF} (Note 14)	Time the Bus Must be Free Before the Start of a New Transmission	SDA crossing 70% of V_{CC} during a STOP condition, to SDA crossing 70% of V_{CC} during the following START condition.	1300			ns
^t LOW	Clock LOW Time	Measured at the 30% of V_{CC} crossing.	1300			ns
t _{HIGH}	Clock HIGH Time	Measured at the 70% of V_{CC} crossing.	600			ns
t _{SU:STA}	START Condition Setup Time	SCL rising edge to SDA falling edge. Both crossing 70% of $V_{CC}.$	600			ns
^t HD:STA	START Condition Hold Time	From SDA falling edge crossing 30% of V _{CC} to SCL falling edge crossing 70% of V _{CC} .	600			ns
^t SU:DAT	Input Data Setup Time	From SDA exiting the 30% to 70% of V_{CC} window, to SCL rising edge crossing 30% of V_{CC}	100			ns
t _{HD:DAT}	Input Data Hold Time	From SCL rising edge crossing 70% of V_{CC} to SDA entering the 30% to 70% of V_{CC} window.	0			ns
tsu:sto	STOP Condition Setup Time	From SCL rising edge crossing 70% of V_{CC} , to SDA rising edge crossing 30% of V_{CC} .	600			ns



SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP (Note 1)	МАХ	UNITS
^t HD:STO	STOP Condition Hold Time for Read, or Volatile Only Write	From SDA rising edge to SCL falling edge. Both crossing 70% of $\rm V_{CC}.$	600			ns
t _{DH} (Note 14)	Output Data Hold Time	From SCL falling edge crossing 30% of V _{CC} , until SDA enters the 30% to 70% of V _{CC} window.	0			ns
t _R (Note 14)	SDA and SCL Rise Time	From 30% to 70% of V _{CC}	20 + 0.1 * Cb		250	ns
t _F (Note 14)	SDA and SCL Fall Time	From 70% to 30% of V_{CC}	20 + 0.1 * Cb		250	ns
Cb (Note 14)	Capacitive Loading of SDA or SCL	Total on-chip and off-chip	10		400	pF
Rpu (Note 14)	SDA and SCL Bus Pull-Up Resistor Off-Chip	Maximum is determined by t_R and t_F . For Cb = 400pF, max is about 2~2.5k Ω . For Cb = 40pF, max is about 15~20k Ω	1			kΩ

Operating Specifications Over the recommended operating conditions unless otherwise specified. (Continued)

SDA vs SCL Timing



NOTES:

- 2. Typical values are for T_A = +25°C and 3.3V supply voltage.
- 3. LSB: [V(RW)255 V(RW)0]/255. V(RW)255 and V(RW)0 are V(RW) for the DCP register set to FF hex and 00 hex respectively. LSB is the incremental voltage when changing from one tap to an adjacent tap.
- 4. ZS error = V(RW)₀/LSB.
- 5. FS error = $[V(RW)_{255} V_{CC}]/LSB$.
- 6. DNL = $[V(RW)_i V(RW)_{i-1}]/LSB-1$, for i = 1 to 255. i is the DCP register setting.
- 7. INL = (V(RW)_i i LSB V(RW)₀)/LSB, for i = 1 to 255.

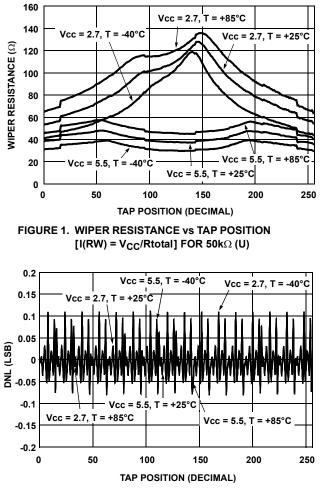
8.
$$TC_{V} = \frac{Max(V(RW)_{i}) - Min(V(RW)_{i})}{[Max(V(RW)_{i}) + Min(V(RW)_{i})]/2} \times \frac{10^{6}}{145^{\circ}C}$$
 for i = 16 to 240 decimal, T = -40°C to +105°C. Max() is the maximum value of the wiper voltage over the temperature range.

- 9. MI = $|R_{255} R_0|/255$. R_{255} and R_0 are the measured resistances for the DCP register set to FF hex and 00 hex respectively. Roffset = R_0/MI , when measuring between RW and RL.
- 10. Roffset = R₂₅₅/MI, when measuring between RW and RH.
- 11. RDNL = $(R_i R_{i-1})/MI$, for i = 32 to 255.
- 12. RINL = $[R_i (MI \cdot i) R_0]/MI$, for i = 32 to 255.

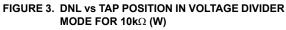
.

13. $TC_{R} = \frac{[Max(Ri) - Min(Ri)]}{[Max(Ri) + Min(Ri)]/2} \times \frac{10^{6}}{145^{\circ}C}$ for i = 32 to 255, T = -40°C to +105°C. Max() is the maximum value of the resistance and Min() is the minimum value of the resistance over the temperature range.

14. This parameter is not 100% tested.







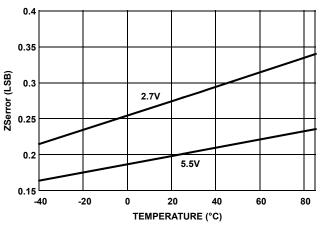


FIGURE 5. ZSerror vs TEMPERATURE

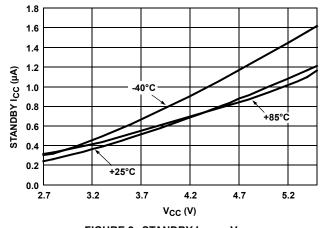
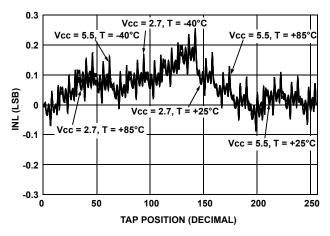
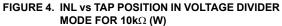


FIGURE 2. STANDBY ICC vs VCC





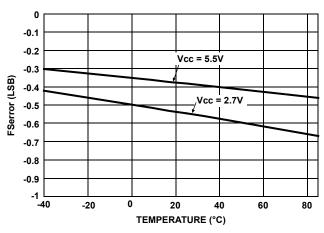


FIGURE 6. FSerror vs TEMPERATURE

Typical Performance Curves (Continued)

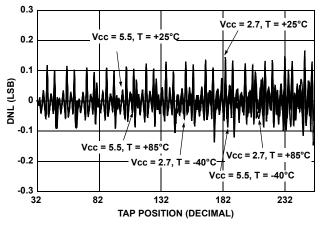
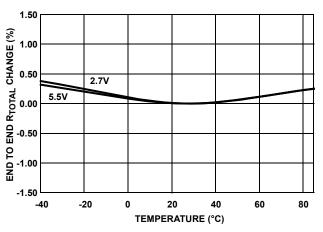
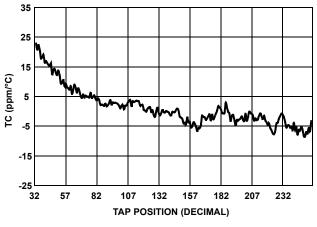


FIGURE 7. DNL vs TAP POSITION IN RHEOSTAT MODE FOR 50k Ω (U)









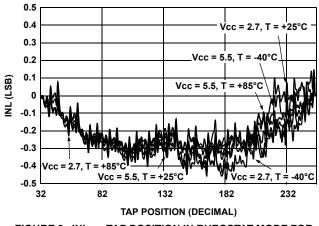


FIGURE 8. INL vs TAP POSITION IN RHEOSTAT MODE FOR 50k Ω (U)

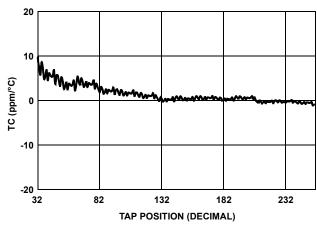


FIGURE 10. TC FOR VOLTAGE DIVIDER MODE IN ppm

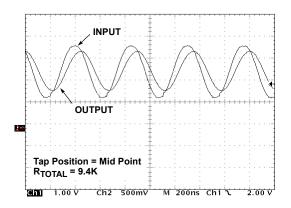
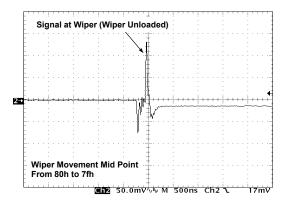


FIGURE 12. FREQUENCY RESPONSE (2.2MHz)

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Typical Performance Curves (Continued)





Principles of Operation

The ISL90810 is an integrated circuit incorporating one DCP with its associated registers, and an I^2C serial interface providing direct communication between a host and the potentiometer.

DCP Description

The DCP is implemented with a combination of resistor elements and CMOS switches. The physical ends of the DCP are equivalent to the fixed terminals of a mechanical potentiometer (RH and RL pins). The RW pin of the DCP is connected to intermediate nodes, and is equivalent to the wiper terminal of a mechanical potentiometer. The position of the wiper terminal within the DCP is controlled by an 8-bit volatile Wiper Register (WR). When the WR of the DCP contains all zeroes (WR[7:0]: 00h), its wiper terminal (RW) is closest to its "Low" terminal (RL). When the WR of the DCP contains all ones (WR[7:0]: FFh), its wiper terminal (RW) is closest to its "High" terminal (RH). As the value of the WR increases from all zeroes (0 decimal) to all ones (255 decimal), the wiper moves monotonically from the position closest to RL to the closest to RH. At the same time, the resistance between RW and RL increases monotonically, while the resistance between RH and RW decreases monotonically.

While the ISL90810 is being powered up, The WR is reset to 80h (128 decimal), which locates RW roughly at the center between RL and RH.

The WR can be read or written to directly using the I^2C serial interface as described in the following sections. The I^2C interface Address Byte has to be set to 00hex to access the WR.

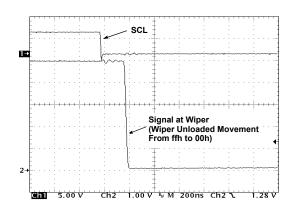


FIGURE 14. LARGE SIGNAL SETTLING TIME

PC Serial Interface

The ISL90810 supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is a master and the device being controlled is the slave. The master always initiates data transfers and provides the clock for both transmit and receive operations. Therefore, the ISL90810 operates as a slave device in all applications.

All communication over the I^2C interface is conducted by sending the MSB of each byte of data first.

Protocol Conventions

Data states on the SDA line must change only during SCL LOW periods. SDA state changes during SCL HIGH are reserved for indicating START and STOP conditions (See Figure 15). On power-up of the ISL90810 the SDA pin is in the input mode.

All I²C interface operations must begin with a START condition, which is a HIGH to LOW transition of SDA while SCL is HIGH. The ISL90810 continuously monitors the SDA and SCL lines for the START condition and does not respond to any command until this condition is met (See Figure 15). A START condition is ignored during the powerup for the device.

All I²C interface operations must be terminated by a STOP condition, which is a LOW to HIGH transition of SDA while SCL is HIGH (See Figure 15) A STOP condition at the end of a read operation, or at the end of a write operation places the device in its standby mode.

An acknowledge (ACK) is a software convention used to indicate a successful data transfer. The transmitting device, either master or slave, releases the SDA bus after transmitting eight bits. During the ninth clock cycle, the receiver pulls the SDA line LOW to acknowledge the reception of the eight bits of data (See Figure 16).



The ISL90810 responds with an ACK after recognition of a START condition followed by a valid Identification Byte, and once again after successful receipt of an Address Byte. The ISL90810 also responds with an ACK after receiving a Data Byte of a write operation. The master must respond with an ACK after receiving a Data Byte of a read operation.

A valid Identification Byte contains 0101000 as the seven MSBs. The LSB is the Read/Write bit. Its value is "1" for a Read operation, and "0" for a Write operation (See Table 1)

The address byte is set to 00h and follows the identification byte. Read and write operations always point to address 00h, indicating the WR for the device.

TABLE 1.	IDENTIFICATION	BYTE FORMAT
	DENTITION	

0	1	0	1	0	0	0	R/W
(MSB)							(LSB)

Write Operation

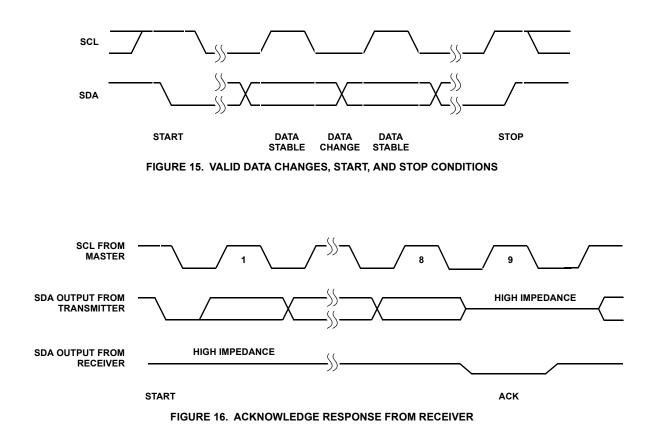
A Write operation requires a START condition, followed by a valid Identification Byte, a valid Address Byte, a Data Byte, and a STOP condition. After each of the three bytes, the ISL90810 responds with an ACK. At this time the device enters its standby state (See Figure 17).

Data Protection

A valid Identification Byte. Address Byte, and total number of SCL pulses act as a protection for the registers. During a Write sequence, the Data Byte is loaded into an internal shift register as it is received. The Data Byte is transferred to the Wiper Register (WR) at the falling edge of the SCL pulse that loads the last bit (LSB) of the Data Byte.

Read Operation

A Read operation consists of a three byte instruction followed by one Data Byte (See Figure 18). The master initiates the operation issuing the following sequence: a START, the identification byte with the R/W bit set to "0", an Address Byte, a second START, and a second Identification byte with the R/W bit set to "1". After each of the three bytes, the ISL90810 responds with an ACK. The the ISL90810 transmits Data Bytes as long as the master responds with an ACK during the SCL cycle following the eighth bit of each byte. The master terminates the read operation (issuing a ACK and a STOP condition) following the last bit of the Data Byte (See Figure 18).





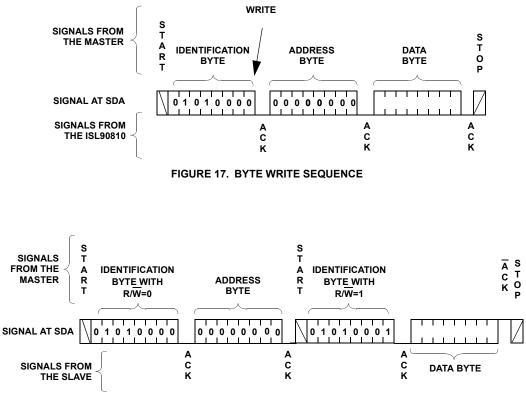


FIGURE 18. READ SEQUENCE



Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

DATE	REVISION	CHANGE
September 10, 2015	FN8234.3	Updated the Ordering Information table on page 1. Added Revision History and About Intersil sections. Updated Package Outline Drawing M8.118 to the latest revision. -Revision 2 to Revision 3 changes - Updated to new intersil format by adding land pattern and moving dimensions from table onto drawing. -Revision 3 to Revision 4 changes - Corrected lead width dimension typo in side view 1 from "0.25 - 0.036" to "0.25 - 0.36".

About Intersil

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For the most updated datasheet, application notes, related documentation and related parts, please see the respective product information page found at <u>www.intersil.com</u>.

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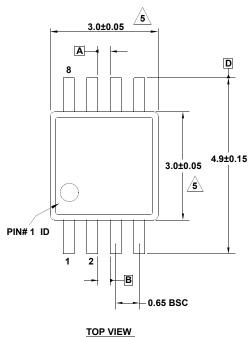


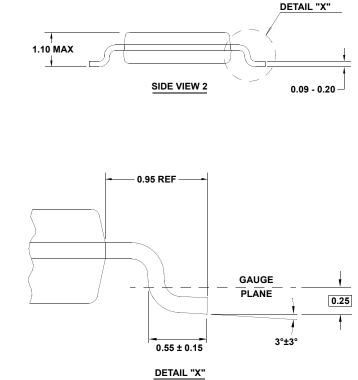
Package Outline Drawing

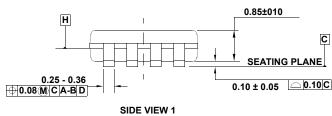
M8.118

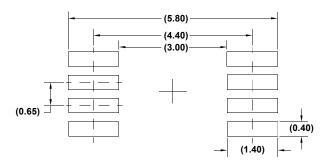
8 LEAD MINI SMALL OUTLINE PLASTIC PACKAGE

Rev 4, 7/11









TYPICAL RECOMMENDED LAND PATTERN

NOTES:

- 1. Dimensions are in millimeters.
- 2. Dimensioning and tolerancing conform to JEDEC MO-187-AA and AMSEY14.5m-1994.
- 3. Plastic or metal protrusions of 0.15mm max per side are not included.
- 4. Plastic interlead protrusions of 0.15mm max per side are not included.
- 5. Dimensions are measured at Datum Plane "H".
- 6. Dimensions in () are for reference only.

